

UG²/EGO 8th Ego Meeting and International Glider Workshop

21 May 2019

Applications of Buoyancy Gliders in the Western Gulf of Mexico

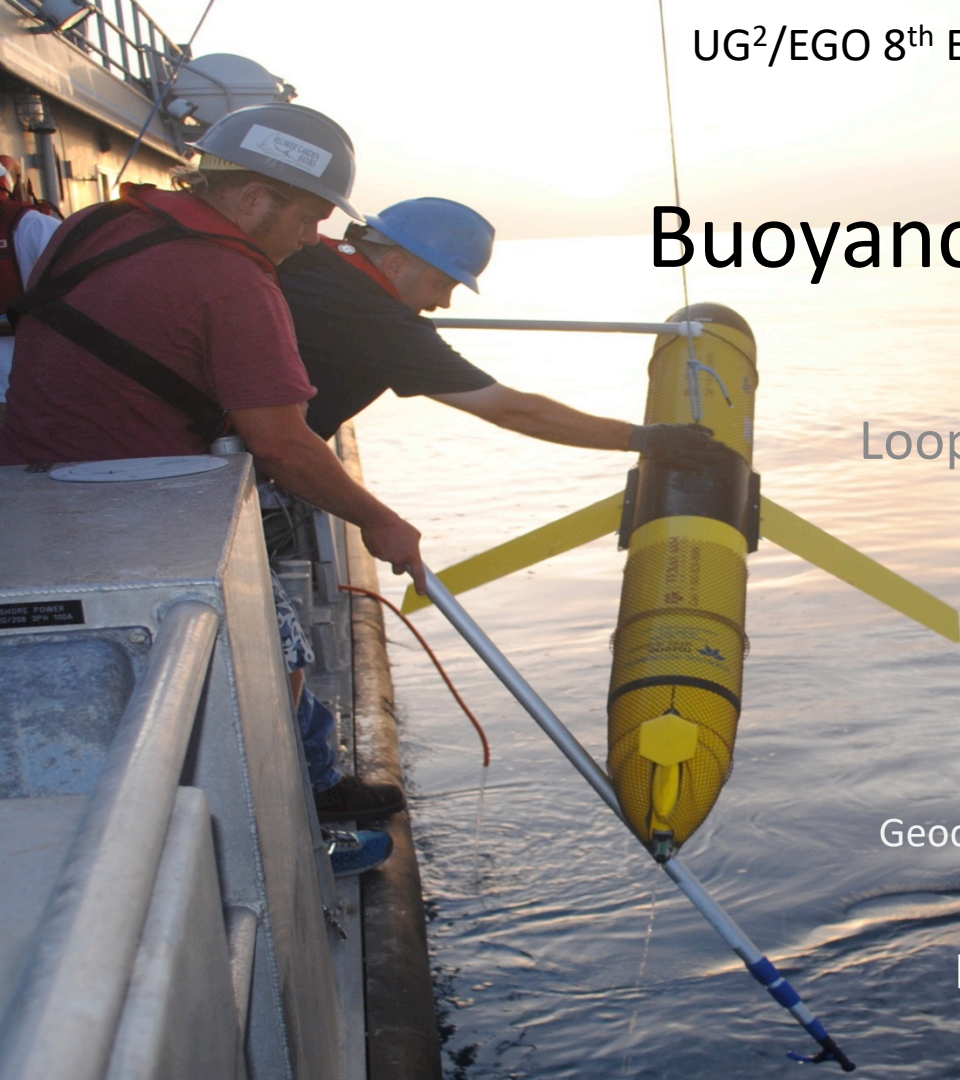
Loop Current Dynamics, Coastal Hypoxia,
Ocean Noise,
Acidification, and Hurricane
Intensification

Steven F. DiMarco

Department of Oceanography and
Geochemical and Environmental Research Group
Texas A&M University

K. Whilden, S. Mahmud, A. H. Knap

RV Manta: 21 June 2014



Glider Research in the Western Gulf of Mexico

- TAMU Capability
- Local Challenges
- Applications
 - Loop Current
 - Coastal Hypoxia, a.k.a. the Deadzone
 - Coral Reef Water Quality
 - Flower Garden Banks
 - Hurricane Harvey (2017)

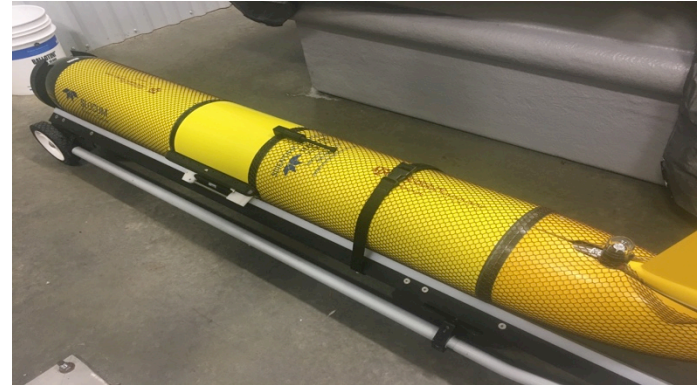
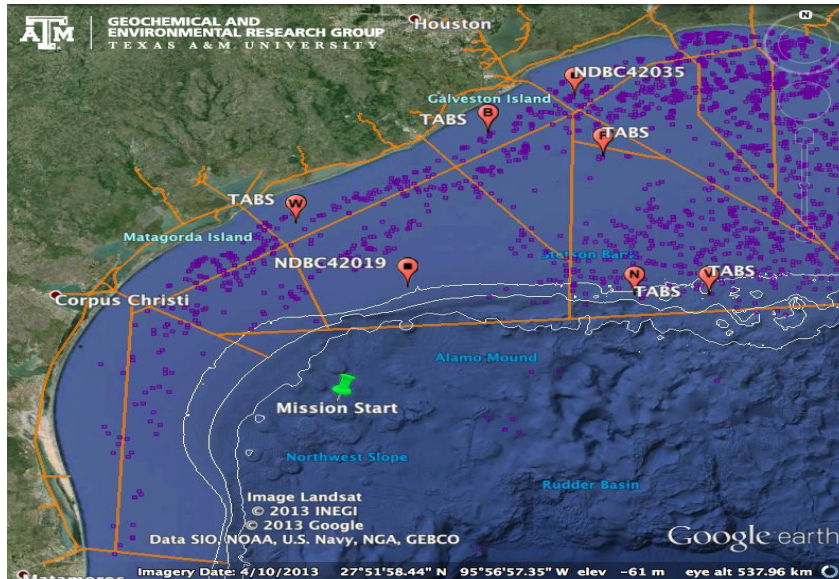
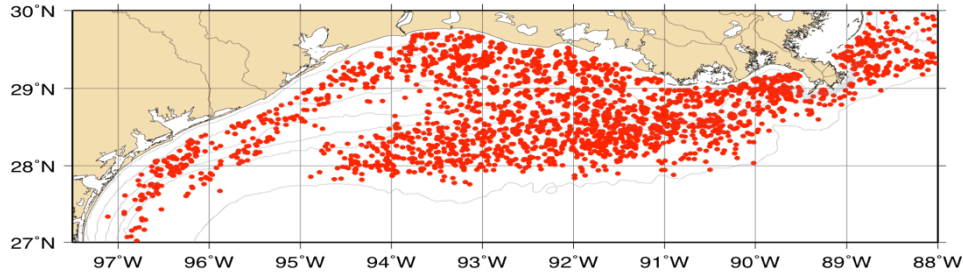


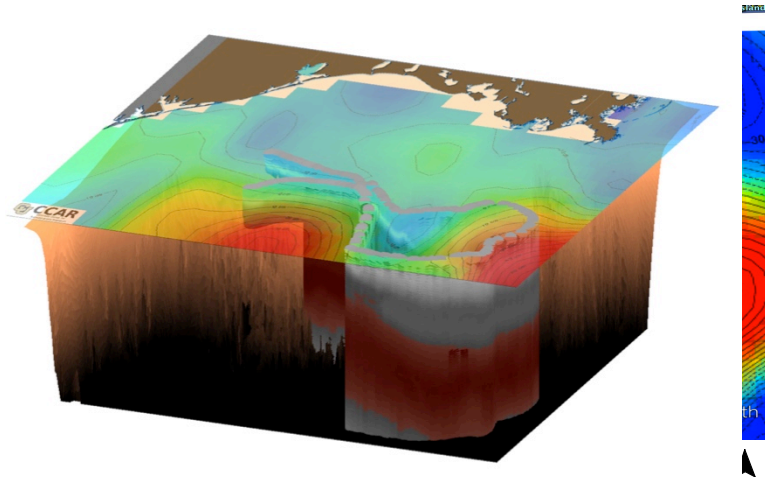
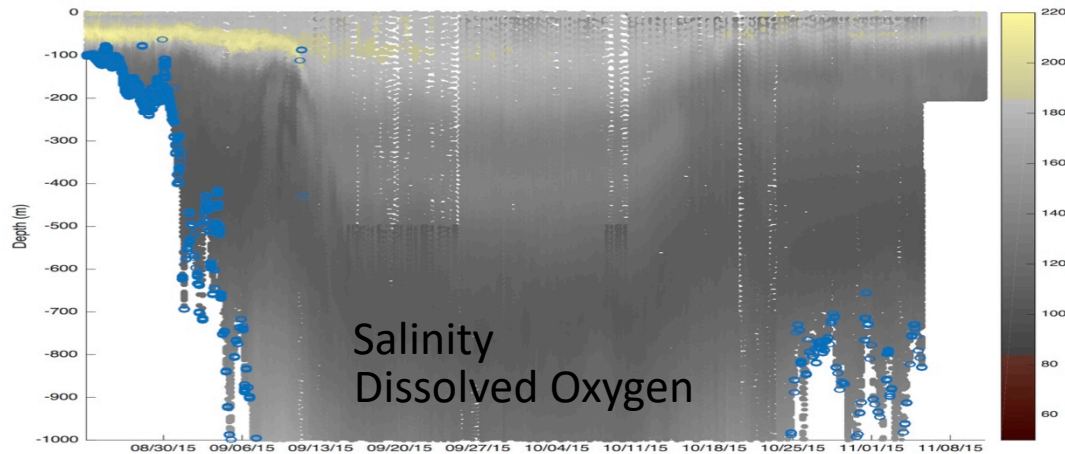
TAMU Glider Capabilities

- GERG Center for Autonomous Vehicle Engineering
 - 5000 sq ft
 - Two ballasting tanks
 - Est. 2012
 - 4 Slocum, 1 Waveglider, 1 Autonaut
- Research Foci
 - Hypoxia, HAB
 - Oil spill response
 - Upper ocean heat content, hurricane response
 - Improvements to prediction
 - Ocean Acoustics
- Western Gulf of Mexico
 - Texas-Louisiana Shelf
 - DWH Spill Site
 - Deep Gulf of Mexico



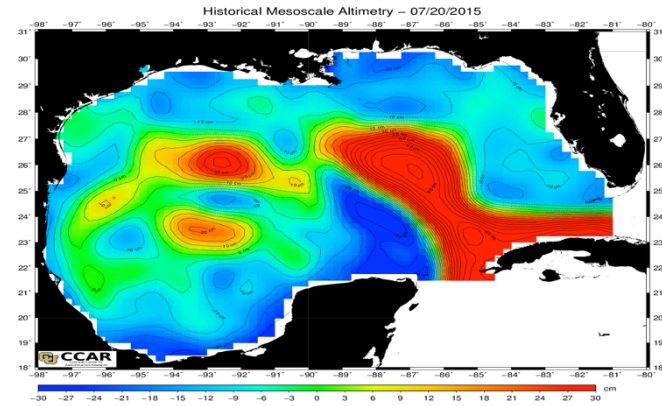
Glider Challenges





Glider Applications

**PREDICTION: UPPER
OCEAN HEAT CONTENT
AND EDDY DYNAMICS**



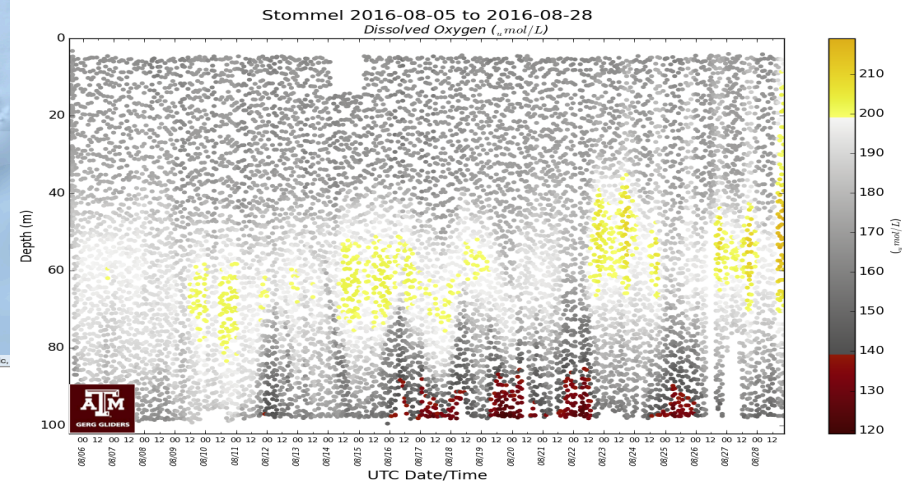
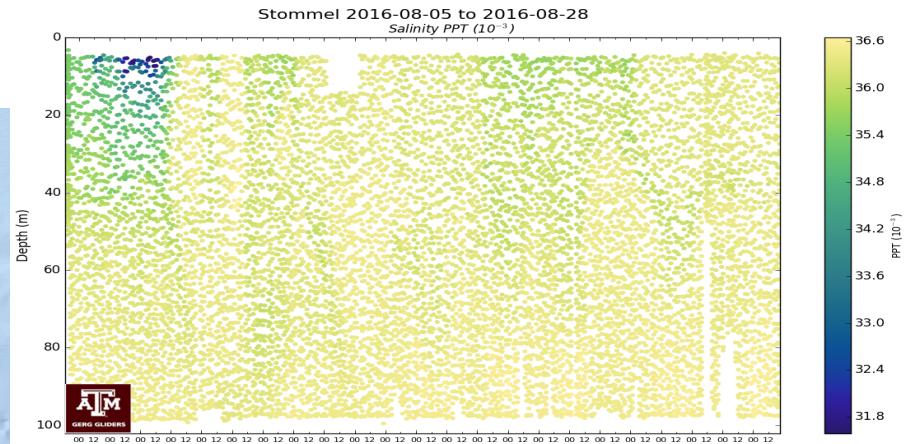
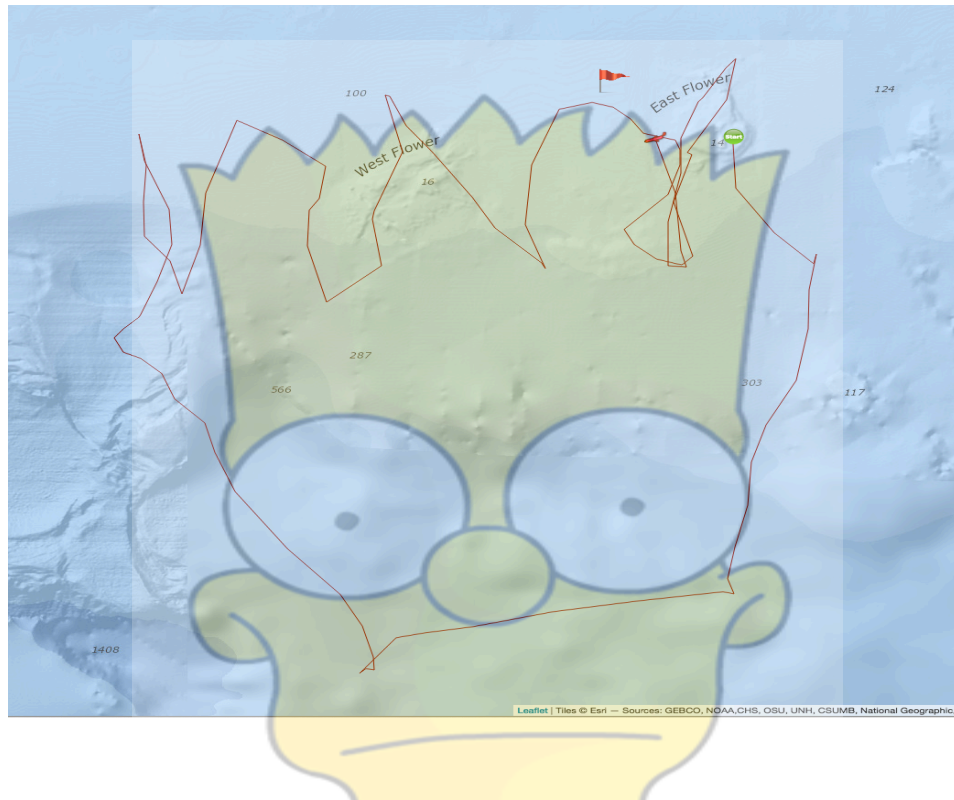


Glider Applications

RESPONSE: FLOWER GARDEN BANKS NMS MORTALITY EVENT

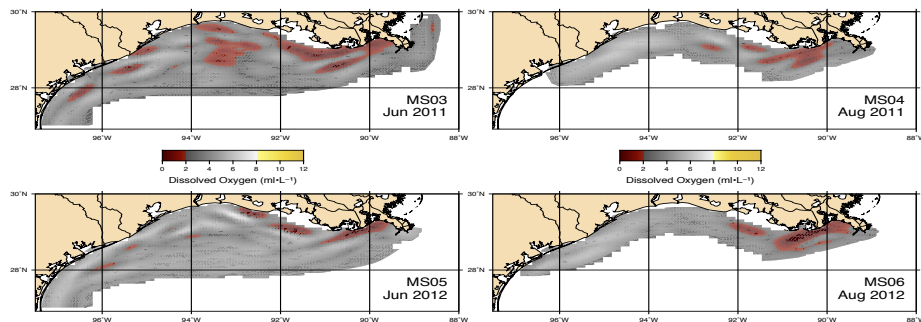


FGB: mortality event track; 2016

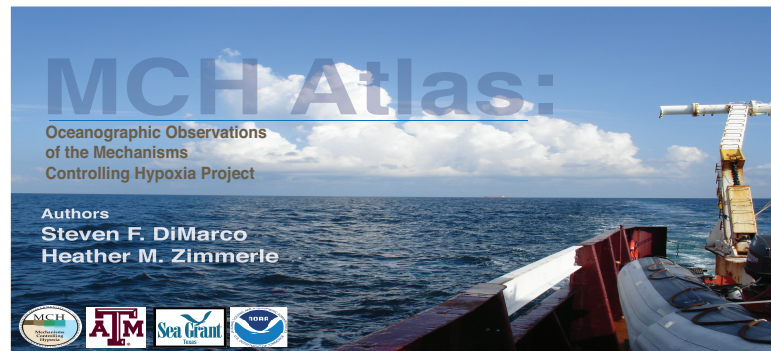


MS03–MS06

Bottom Dissolved Oxygen



<http://mchatlas.tamu.edu>



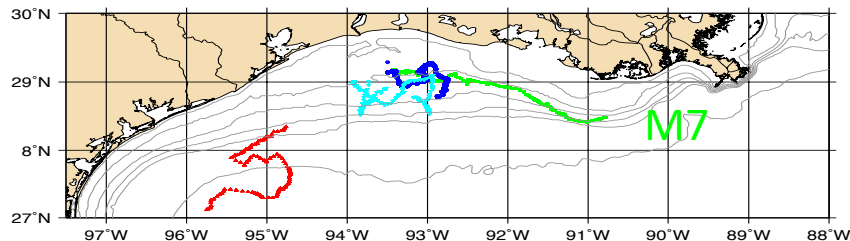
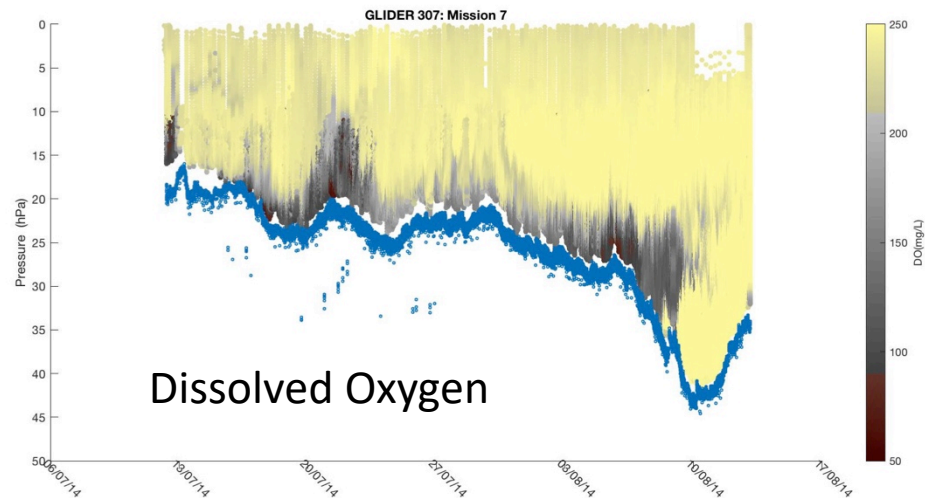
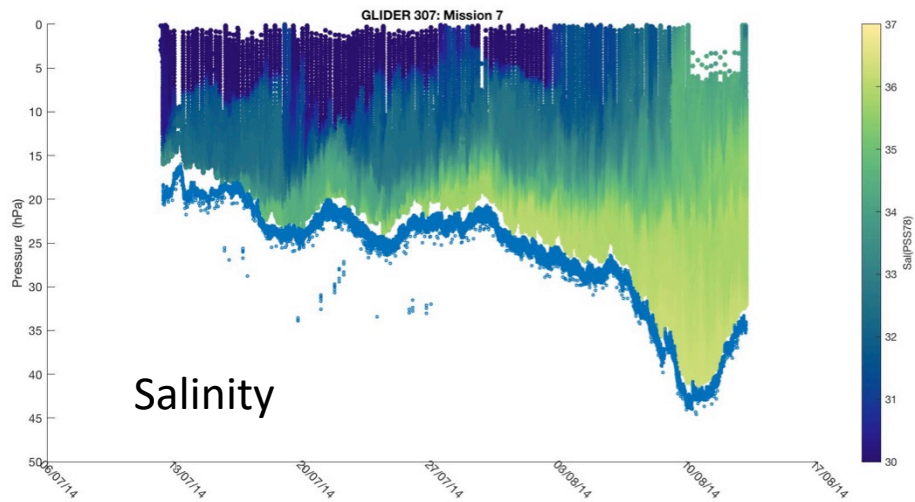
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Glider Applications

COASTAL HYPOXIA

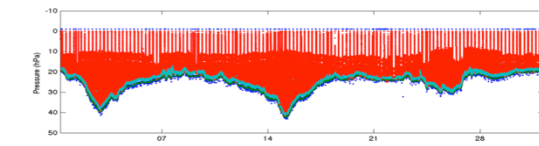
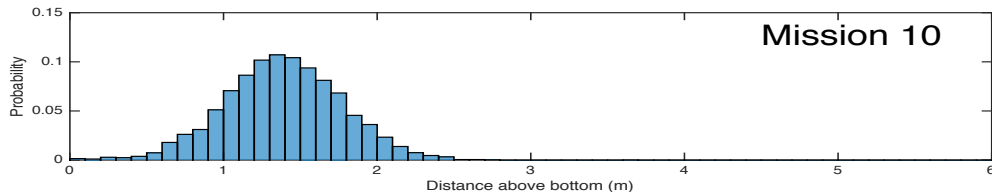
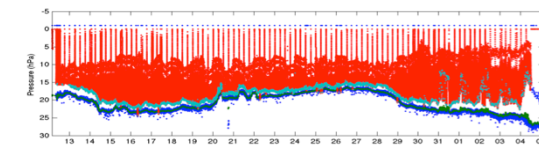
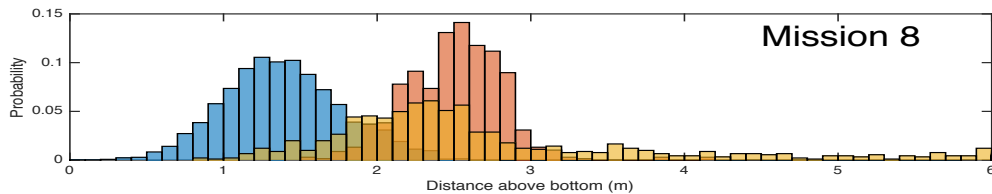
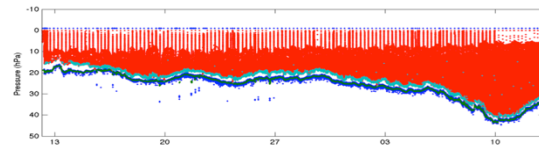
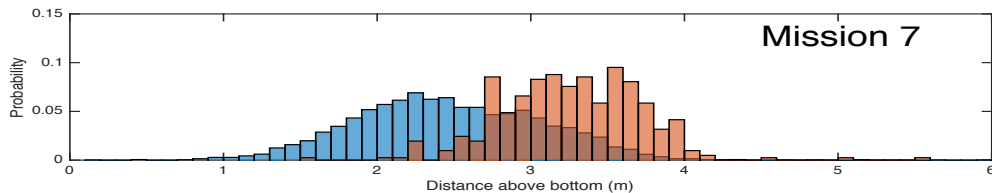
Gulf Glider Hypoxia Experiment

Summer 2014



Ramey et al. 2017 (MTSJ)

How close to the bottom?



Hurricane Harvey: 25 August 2017

Intensification: Potter et al. 2019 (JGR-Oceans)



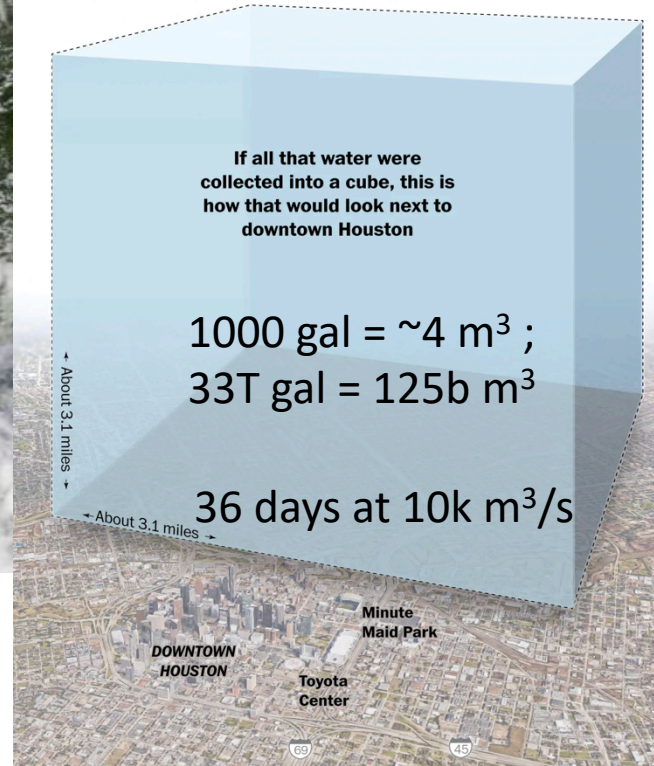
First landfall near Rockport TX

Cat 4 Hurricane on 25 August 2017

Second landfall near Cameron, LA on 29 August 2017

What would 33 trillion gallons of water look like?

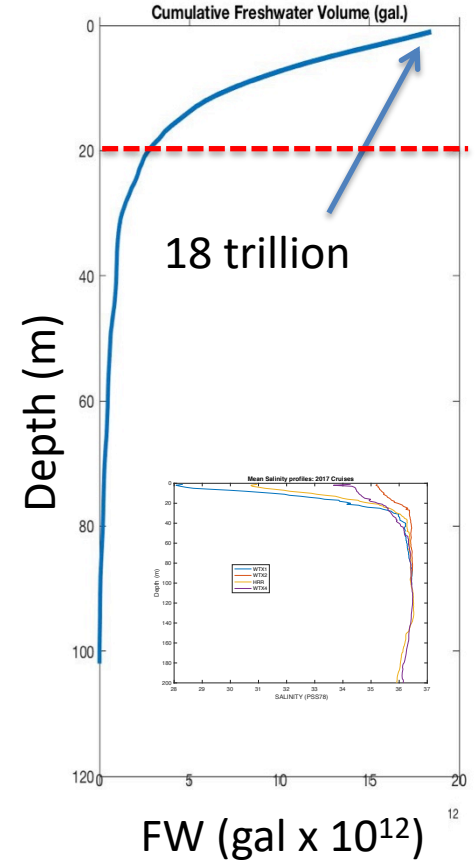
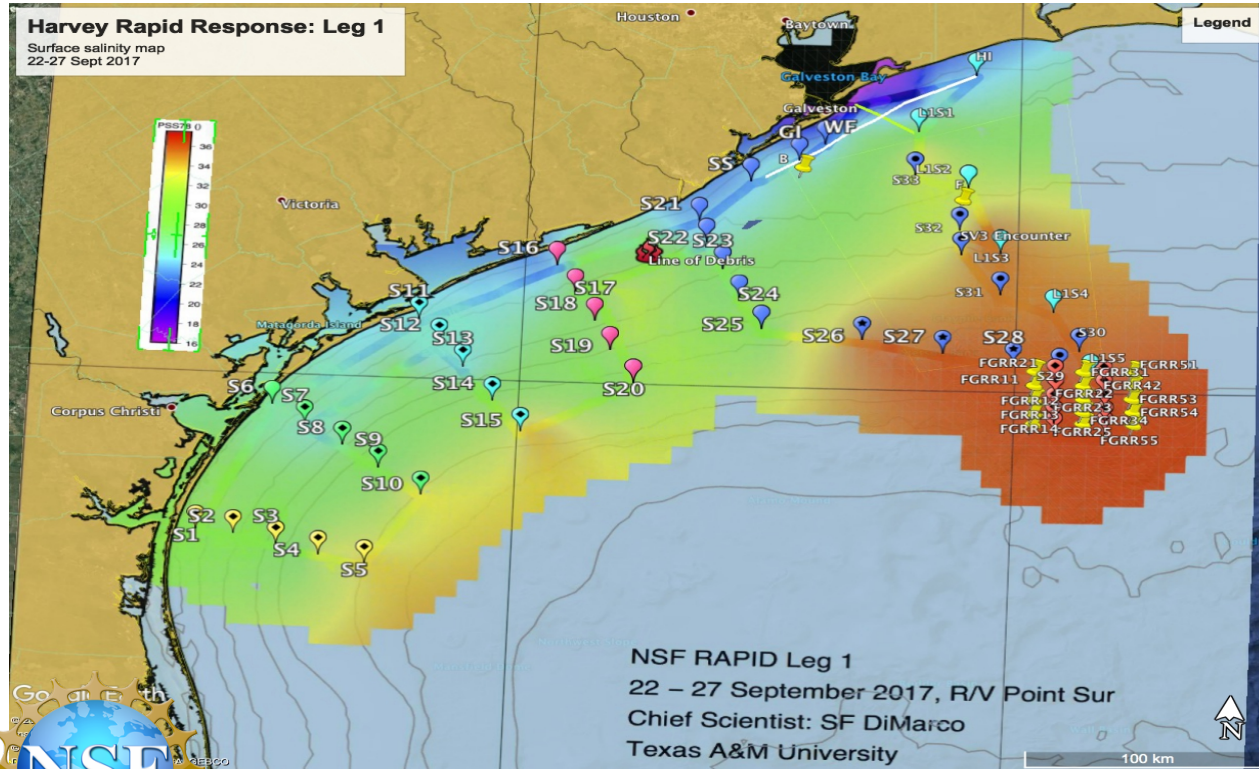
As of Saturday, Sep. 1, about 33 trillion gallons of rain have fallen along the Gulf of Mexico.

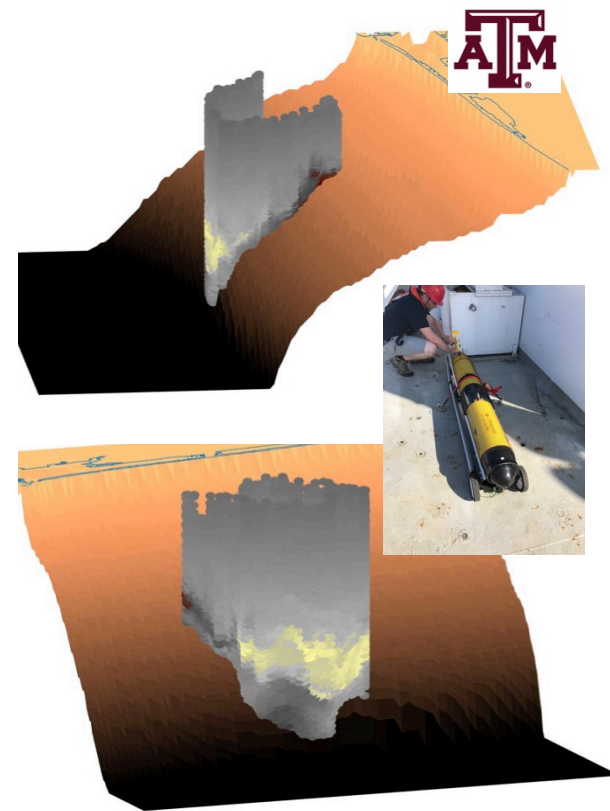
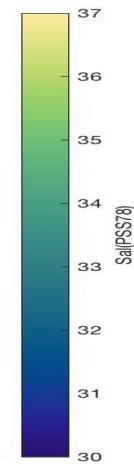
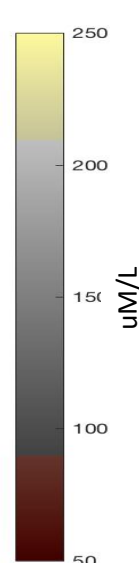
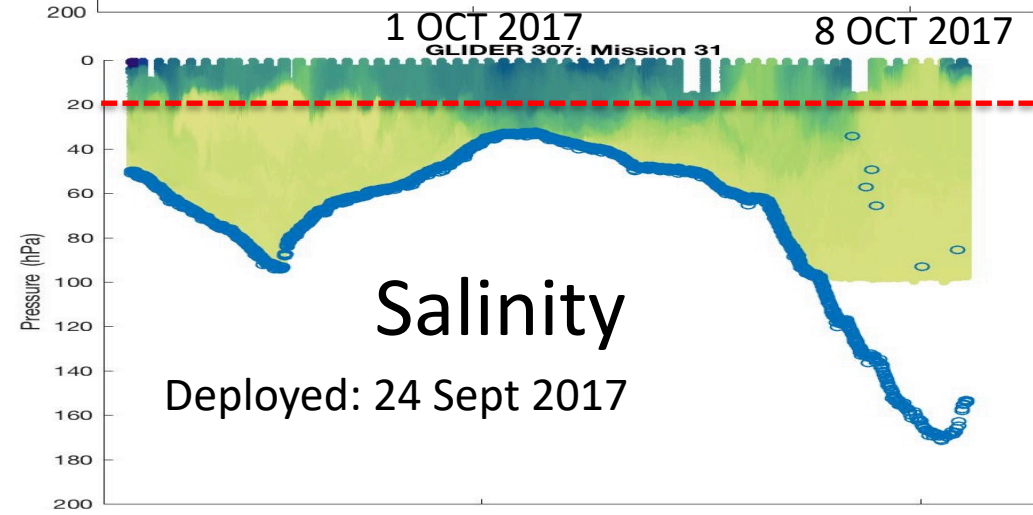
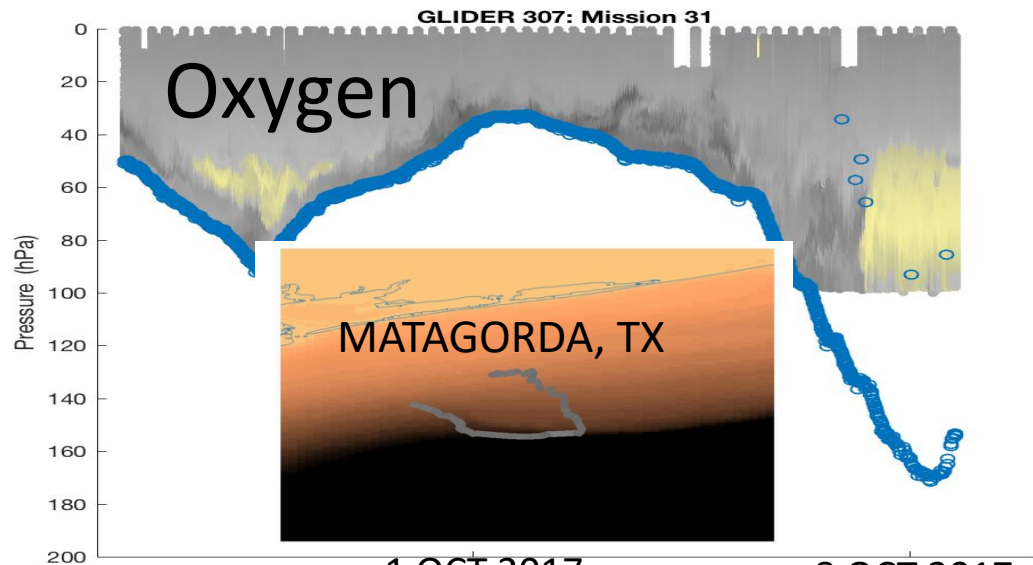


Sources: Ryan Maue, Capital Weather Gang, Google Earth

THE WASHINGTON POST

Hurricane Harvey: Freshwater Volume





Slocum Glider Mission

True Colors of Oceanography

Guidelines for Effective and Accurate Colormap Selection

By Kristen M. Thyng, Chad A. Greene, Robert D. Hetland, Heather M. Zimmerle, and Steven F. DiMarco

UNCORRECTED

or any given type of data. For fields without strong natural color associations such as salinity or wave height, intuition is developed by consistently associating each variable with its own colormap. This principle can hold true within a single manuscript or may be developed over time as a convention, much like the Greek letters we tend to associate with specific oceanographic variables. Just as we do not use σ to represent temperature, density, and salinity within the same manuscript, each variable plotted in a manuscript should be represented by its own colormap.

Consider Colorblind Viewers

Rates of colorblindness are low among women, but among men, approximately 7% of Northern European descendants, 4% of Asian descendants, and 3% of African descendants have some form of

red-green colorblindness (Sharpe et al., 1999). For colorblind viewers, reds and greens of similar lightness values can be difficult to discern. Figure 1f shows example colormaps as perceived with a moderate (50%) deuteranomaly, which is the most common form of color deficiency. The *gray*, *haline*, and *balance* colormaps maintain distinct colors with moderate deuteranomaly so that figures plotted with these colormaps will be readable to color-deficient viewers, though the *balance* colormap has changes in red and green values and a shift in the luminance and saturation. The *phase* colormap appears duller without green and red hue variation, but the colors in the colormap still vary smoothly. Note that the severity of the colorblindness will change how these colormaps appear because the changes are nonlinear with severity.

cmocean: AN OCEANOGRAPHIC COLORMAP PACKAGE

Following the guidelines presented above, we have developed a set of perceptually uniform colormaps tailored for use in oceanography. Figure 2 shows the *cmocean* collection, which is composed of several sequential colormaps meant to elicit intuitive understanding of common oceanographic variables; three divergent colormaps; one cyclic colormap; and one hybrid colormap designed for the special case of displaying oxygen saturation. The package combines original colormaps developed specifically for this work with several preexisting colormaps (Moreland, 2009; Niccoli, 2012; Brewer, 2013; Samsel et al., 2015; see Acknowledgments); we have altered these maps for perceptual uniformity using *viscm*. Single-hue and multi-hue colormaps are included, and each of the sequential and diverging colormaps span a wide range of lightness to maximize dynamic range in data display. The *cmocean* colormaps have been given names such as *thermal*, *haline*, and *ice* to help guide users to intuitive colormaps for common oceanographic variables; however, our nomenclature is not intended to restrict usage to any

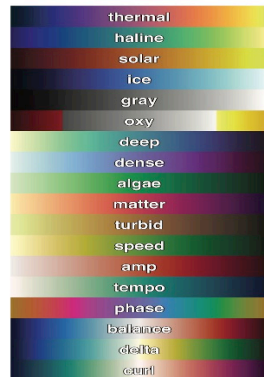


FIGURE 2. Colormaps available in the *cmocean* package.

Color Maps

Thyng et al. 2016: *Oceanography* 29(3): 9-13

Used by US Glider DAC, Austrian Glider DAC, GCOOS

Available at <https://github.com/matplotlib/cmocean>

Supported languages:

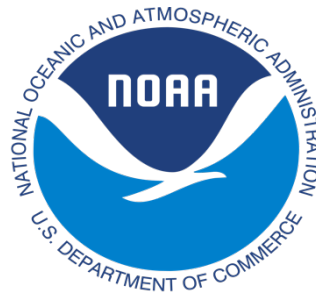
python

MATLAB

ODV (Ocean Data View)

GMT (Generic Mapping Tools)

Acknowledgements



Private/Public Partnerships