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NAVOCEANO Glider Operations An Update for 2011

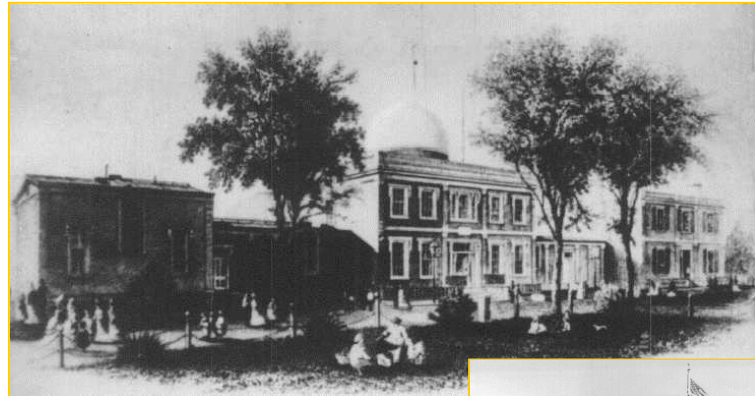


**Ken Grembowicz
Ocean Sciences Division
2011 European Glider Observatory (EGO) Meeting
17 March 2011**



Naval Oceanographic Office

History and Milestones

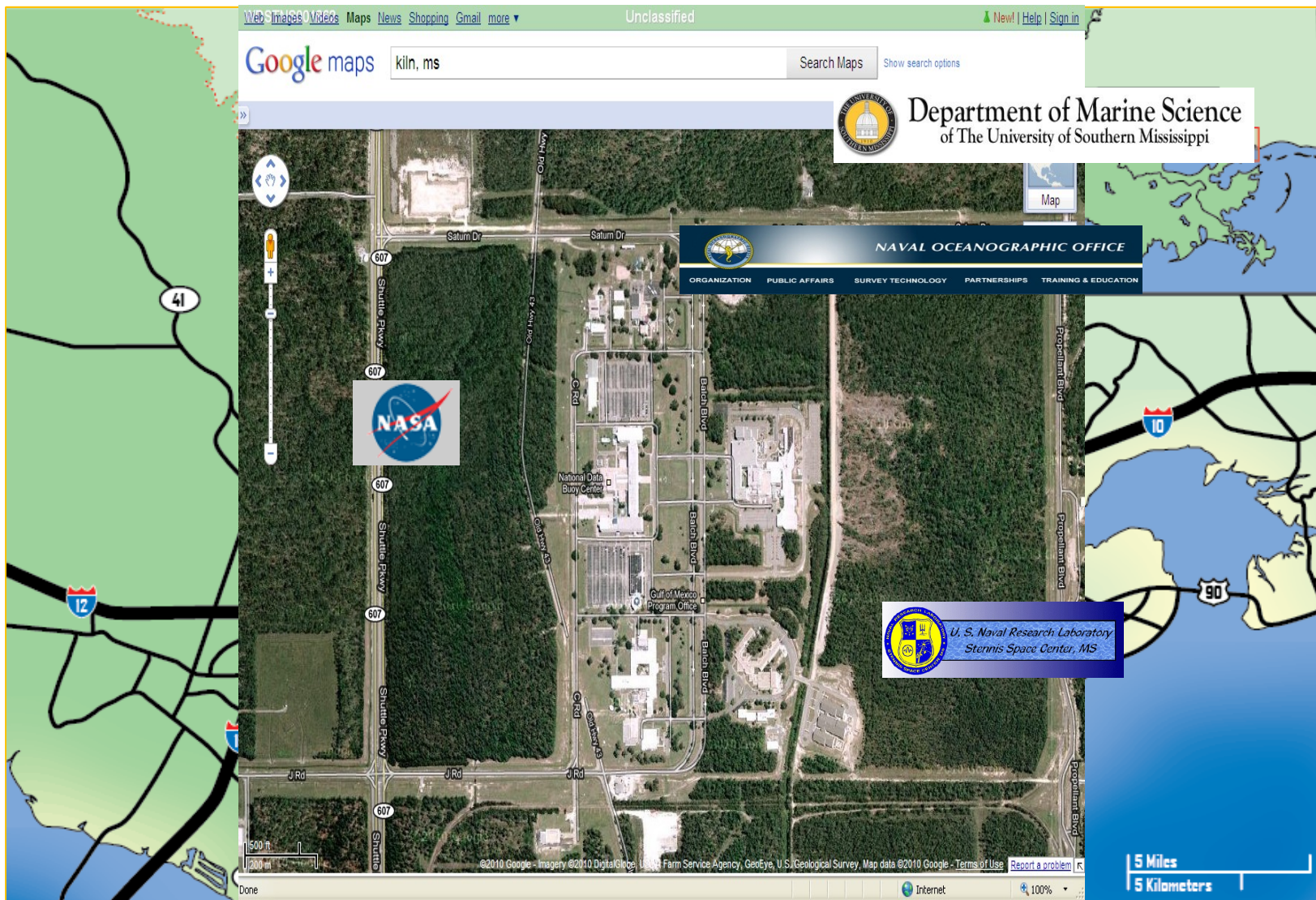


- **1830** Depot of Charts and Instruments established; later renamed U.S. Hydrographic Office
- **1962** Renamed U.S. Naval Oceanographic Office
- **1977** Relocated from Washington, D.C. to Stennis Space Center
- **1987** Operational Oceanography Center established
- **1991** Supercomputer became operational
- **1994** T-AGS 60 Class military survey ships became operational
- **2005** Restructured as Oceanographic Reach-Back Center to support Naval Operations
- **2008** Began Maritime Homeland Defense surveys of U.S. Military installations



Naval Oceanographic Office

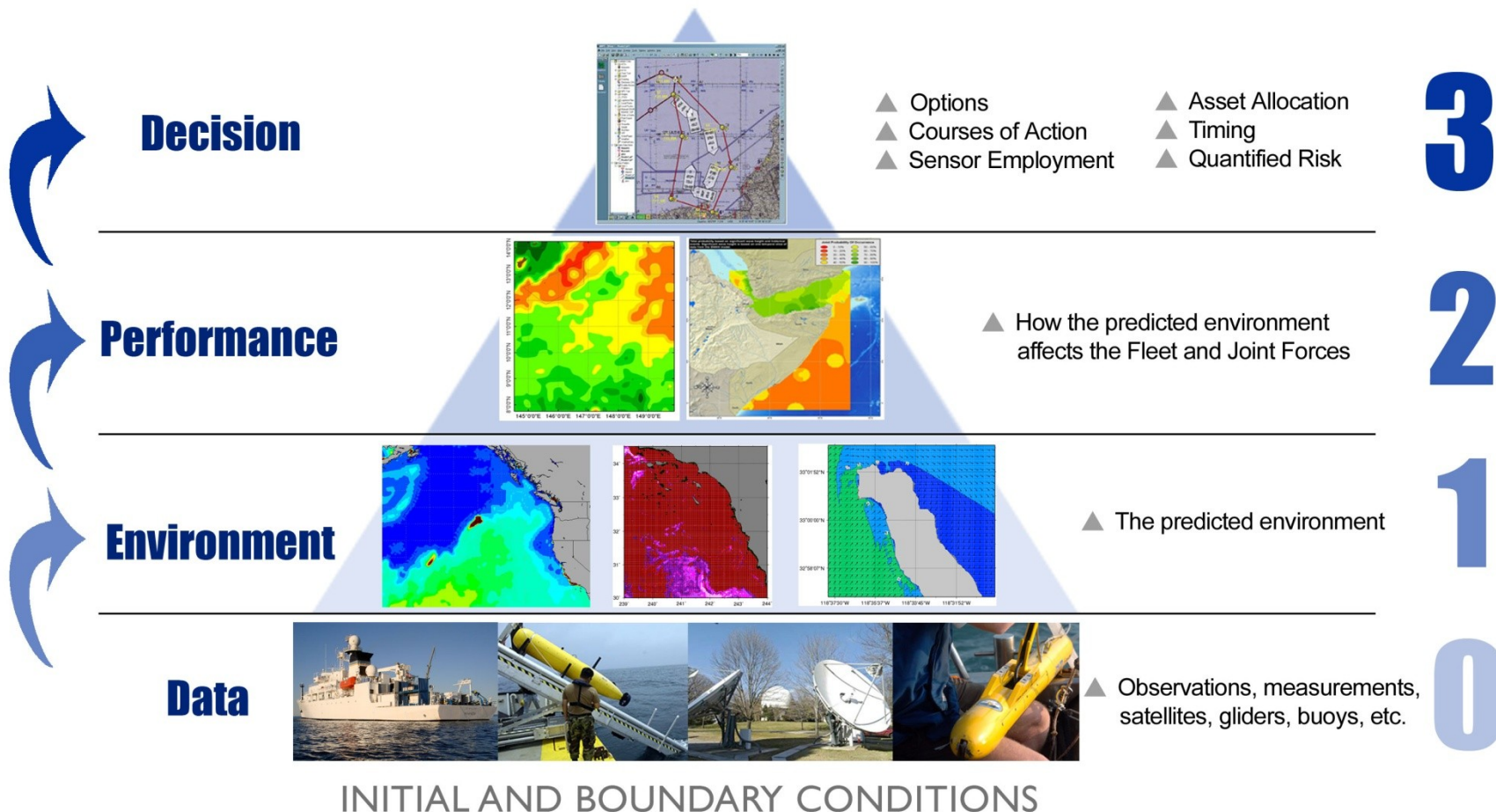
Location



Battlespace On Demand

Linking Data to Decisions

Decision superiority: Making better decisions faster than the adversary





NAVOCEANO Glider Team



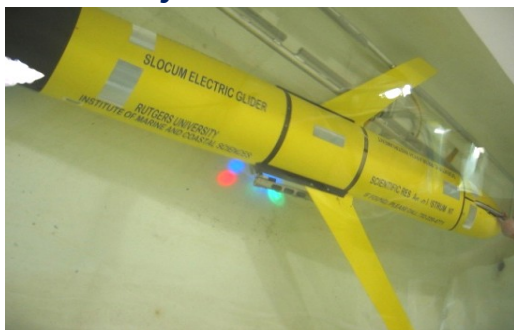


NAVOCEANO Glider Systems



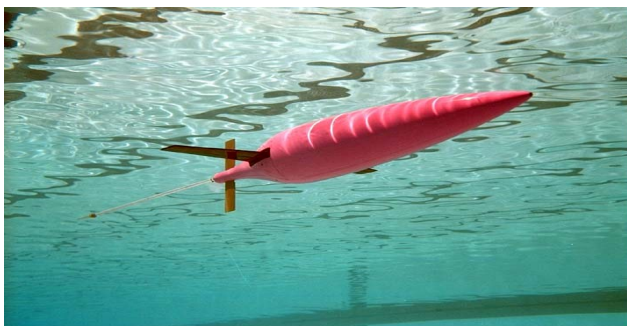
Slocum Glider

Teledyne Webb Research



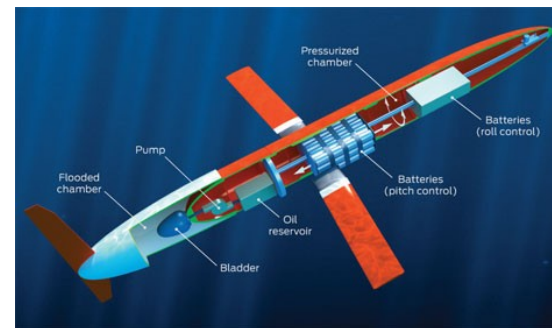
Seaglider

IROBOT / APL-UW



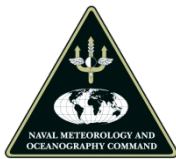
Spray Glider

Scripps Institution of Oceanography



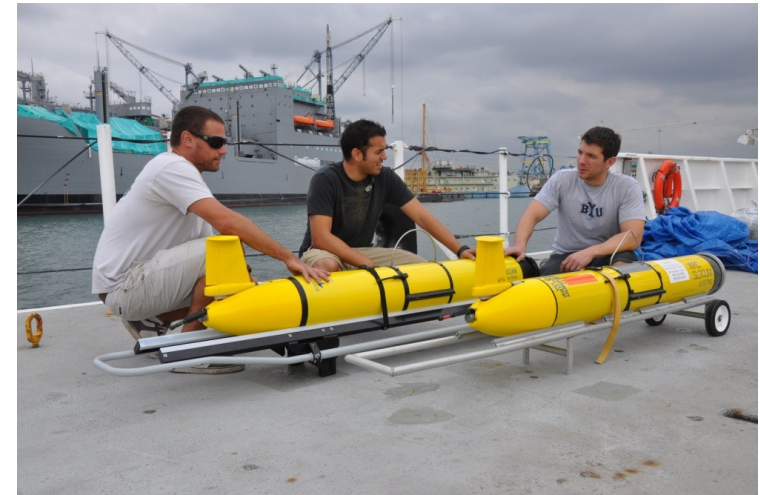
Electric LBS-G

Weight	123 lb	132 lb	110 lb	114 lb
Hull Dia.	21 cm	22 cm	30 cm	20 cm
Length	1.5 m	1.5 m	2.8 m (w/1-m antenna)	2.15 m
Speed	0.6 knots	0.6 knots	0.6 knots	0.6 knots
Max Depth	200 m	1000 m	1000 m	1500 m
Endurance	30 days	4-6 months	4 - 6 months	4 - 5 months
Range	1500 km	4000 km	4500 km	4500 km
Energy	Alkaline	Lithium	Lithium	Lithium
Comms (global)	Iridium	Iridium	Iridium	Iridium

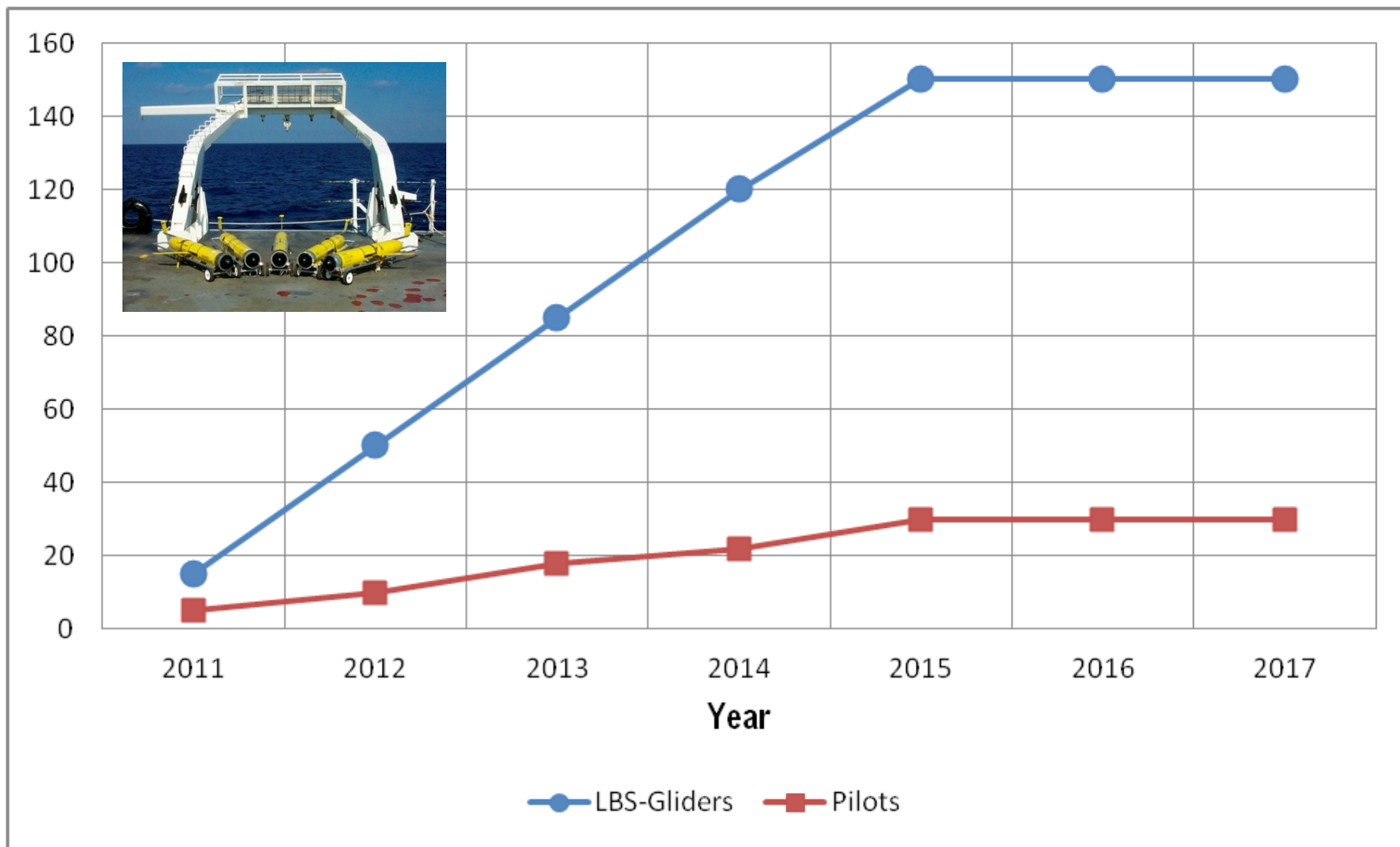


LBS-Glider Specifications

- ❑ ***Oceanographic collection performance requirements***
 - ***Sensor sampling throughout water column (surface - 1000m depth)***
 - ***Periodic surfacing for data transmission and platform tasking***
 - ***Long endurance***
- ❑ ***Sensors payloads:***
 - ***Conductivity, Temperature, and Depth (CTD)***
 - ***Water clarity (beam attenuation)***
 - ***Acoustic Measurements (Spiral 2)***
 - ***Acoustic Doppler Current Profiler (Spiral 2)***



Acquisition Plans





NAVOCEANO Glider Operations

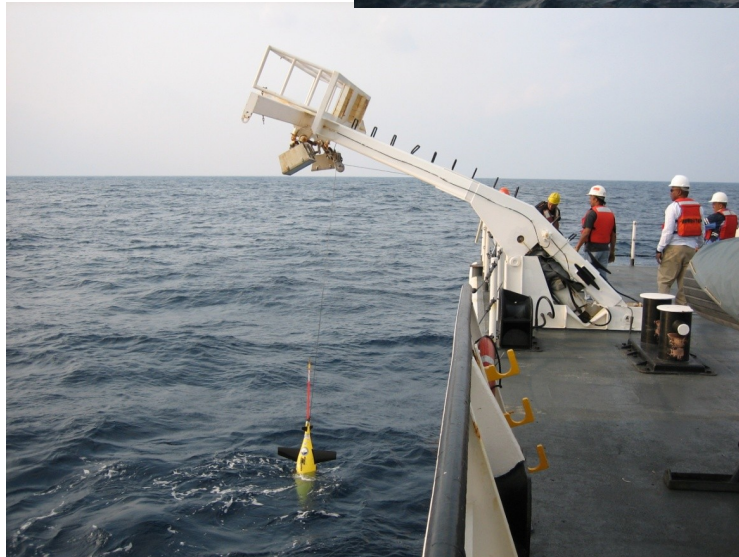


- Glider systems typically launched and recovered from Navy Military Survey Ships.
- Controlled remotely by Glider Operations Center (GOC) pilots located at Stennis Space Center, MS.
- Provides persistent data sampling.
- Optimizes oceanographic feature characterization.
- Produces near real-time





NAVOCEANO Glider Operations





Glider Operations Center



Functions:

- Command & Control (GLMPC)
- Data Validation (LAGER)
- Data Handling (via RTDHS)
- Call center for lost gliders and fleet support.

24/7 Operations





Persistent Sampling Mission



GLMPC Console

Tracks

Dives

Profiles

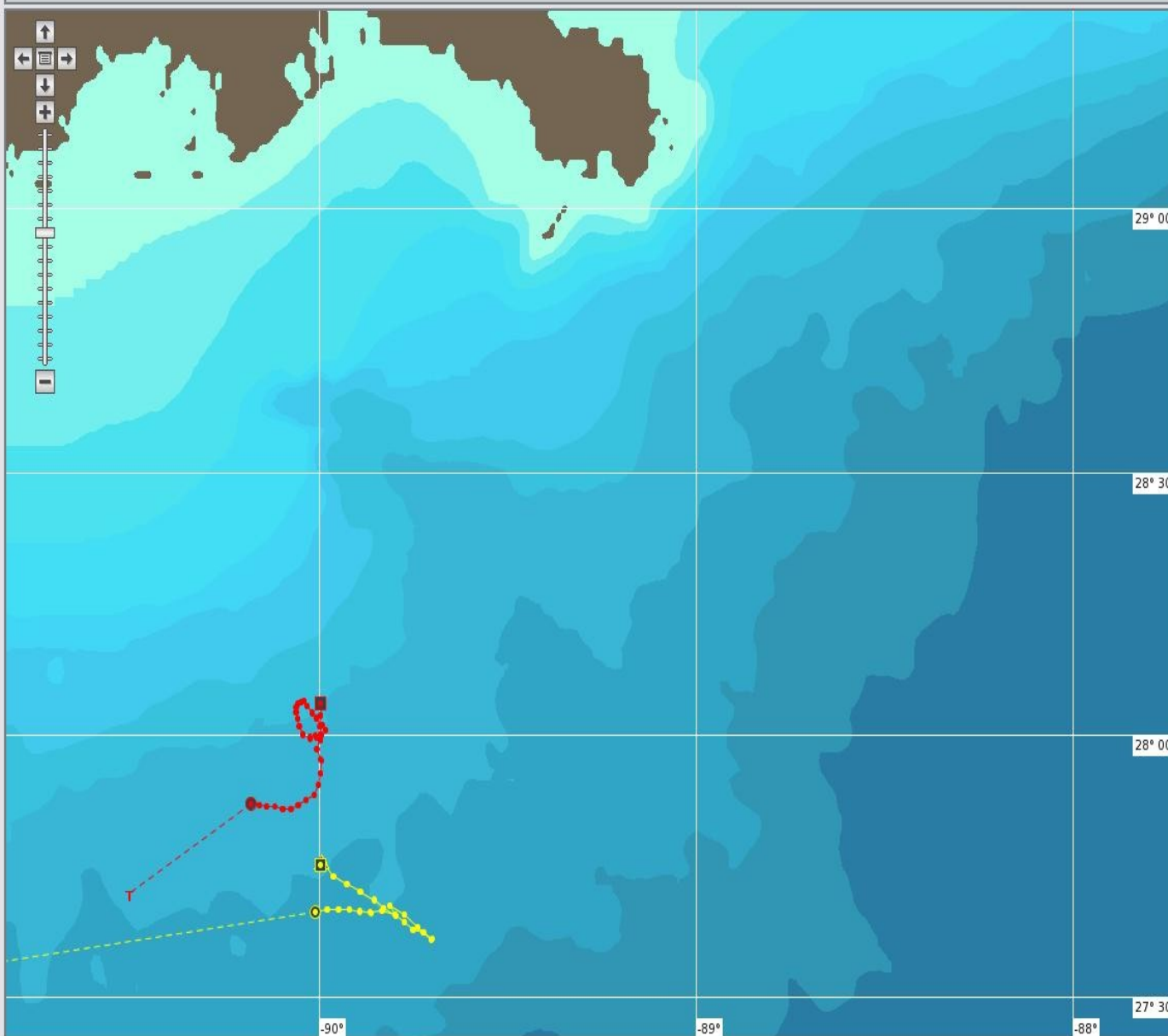
Diagnostics

Control

Routes

Help

No New Messages.

[Show All \(0\)](#)

Glider Status

Glider	Menu	Dive	Due	Health
SG135		33	2041Z	
SG137		51	2056Z	

Track Filter

- ☒ **Growing:** From dive
- ☐ **Sliding:** Last dives
- ☐ **Fixed:** From dive to

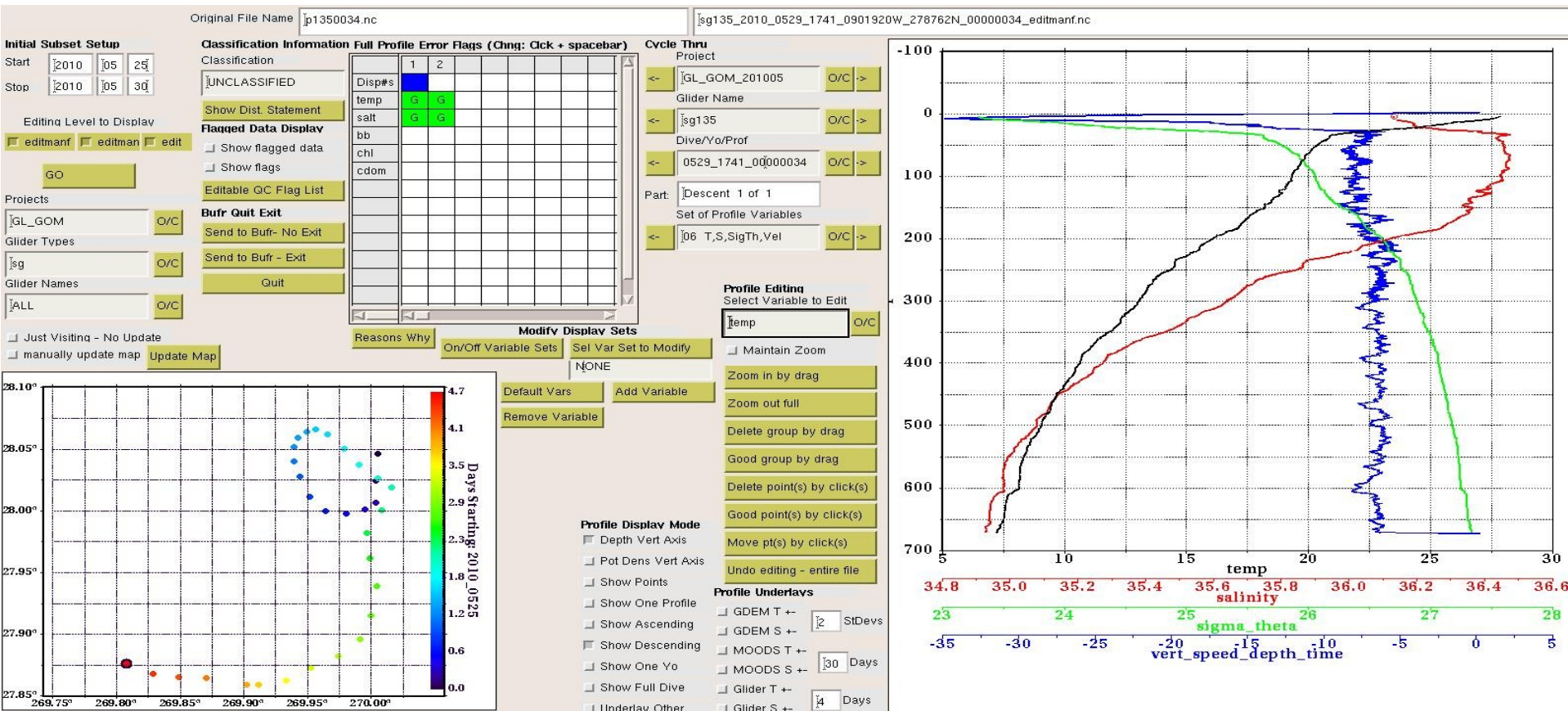
[Update Track](#)

Display Options

Item	Visibility
Graticules	
<input checked="" type="checkbox"/> Grid	<input checked="" type="checkbox"/>
<input checked="" type="checkbox"/> Labels	<input checked="" type="checkbox"/>
SG135	
<input checked="" type="checkbox"/> DAC	<input type="checkbox"/>
<input checked="" type="checkbox"/> Route	<input type="checkbox"/>
<input checked="" type="checkbox"/> Track	<input checked="" type="checkbox"/>
SG137	
<input checked="" type="checkbox"/> DAC	<input type="checkbox"/>
<input checked="" type="checkbox"/> Route	<input type="checkbox"/>
<input checked="" type="checkbox"/> Track	<input checked="" type="checkbox"/>



LAGER





Gulf of Mexico Mission



Objectives:

- Accelerate implementation of R-NCOM for the Gulf of Mexico
- Provide ocean circulation forecasts NOAA OR&R and IOOS
- Utilize glider systems to determine the presence of subsurface oil



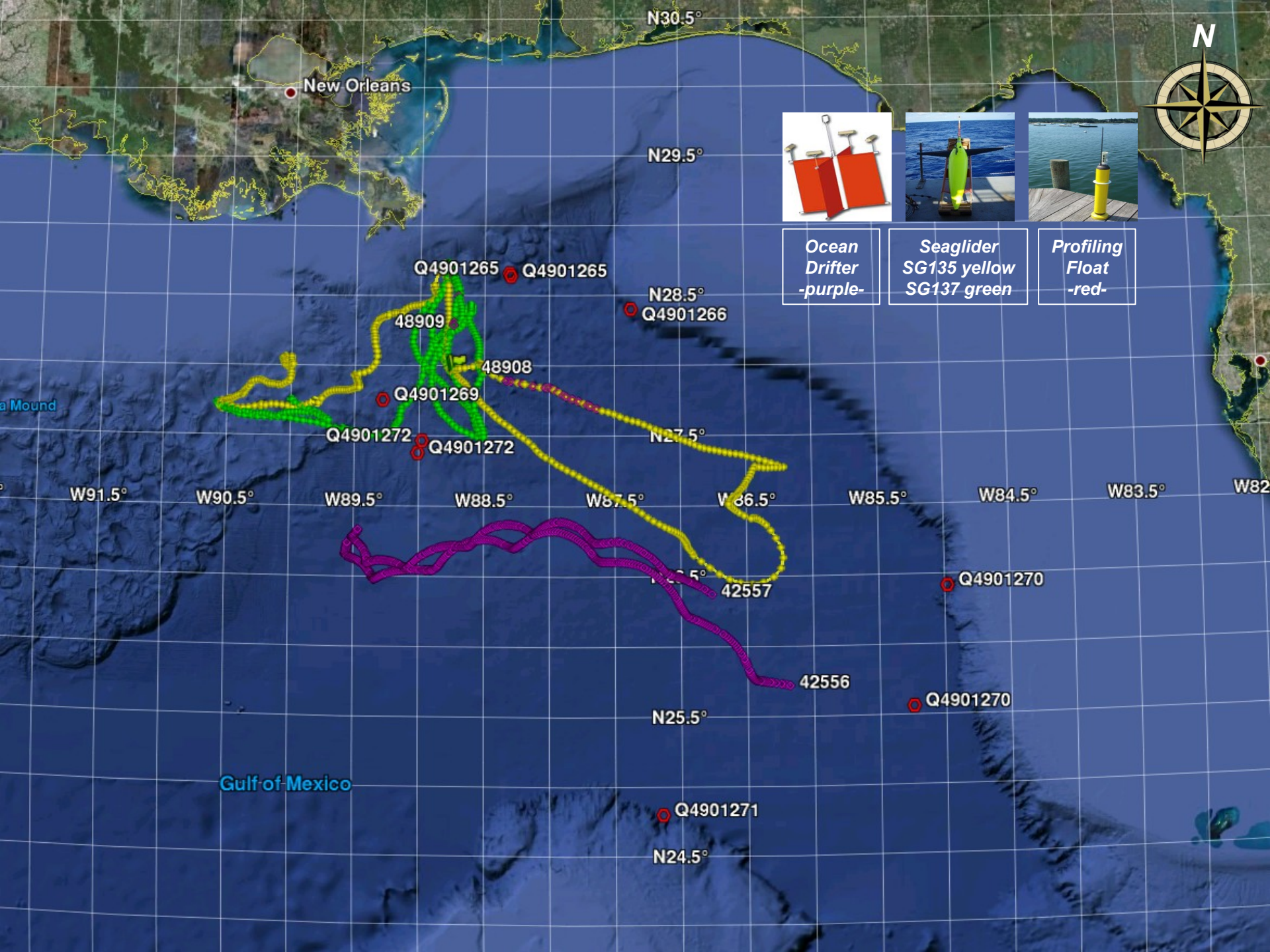
Oceanographic Instrumentation:

- Two (2) iRobot Seagliders rapidly oceanographic with WET Labs ECO pucks (CDOM)
- Eleven (11) Teledyne Webb Research APEX floats
- Eighteen (18) MetOcean surface drifters

Deployment and Recovery Vessels:

- R/V Thomas Jefferson (25 May 2010)
- R/V Henry B. Bigelow (19 Aug 2010)





New Orleans

N30.5°

N29.5°

N28.5°

N27.5°

N26.5°

N25.5°

N24.5°

Q4901265

48909

48908

Q4901269

Q4901272

Q4901272

Q4901266

W91.5°

W90.5°

W89.5°

W88.5°

W87.5°

W86.5°

W85.5°

W84.5°

W83.5°

W82°

Q4901270

Q4901270

Q4901271

42556

42557

Gulf of Mexico



Ocean Drifter
-purple-



Seaglider
SG135 yellow
SG137 green



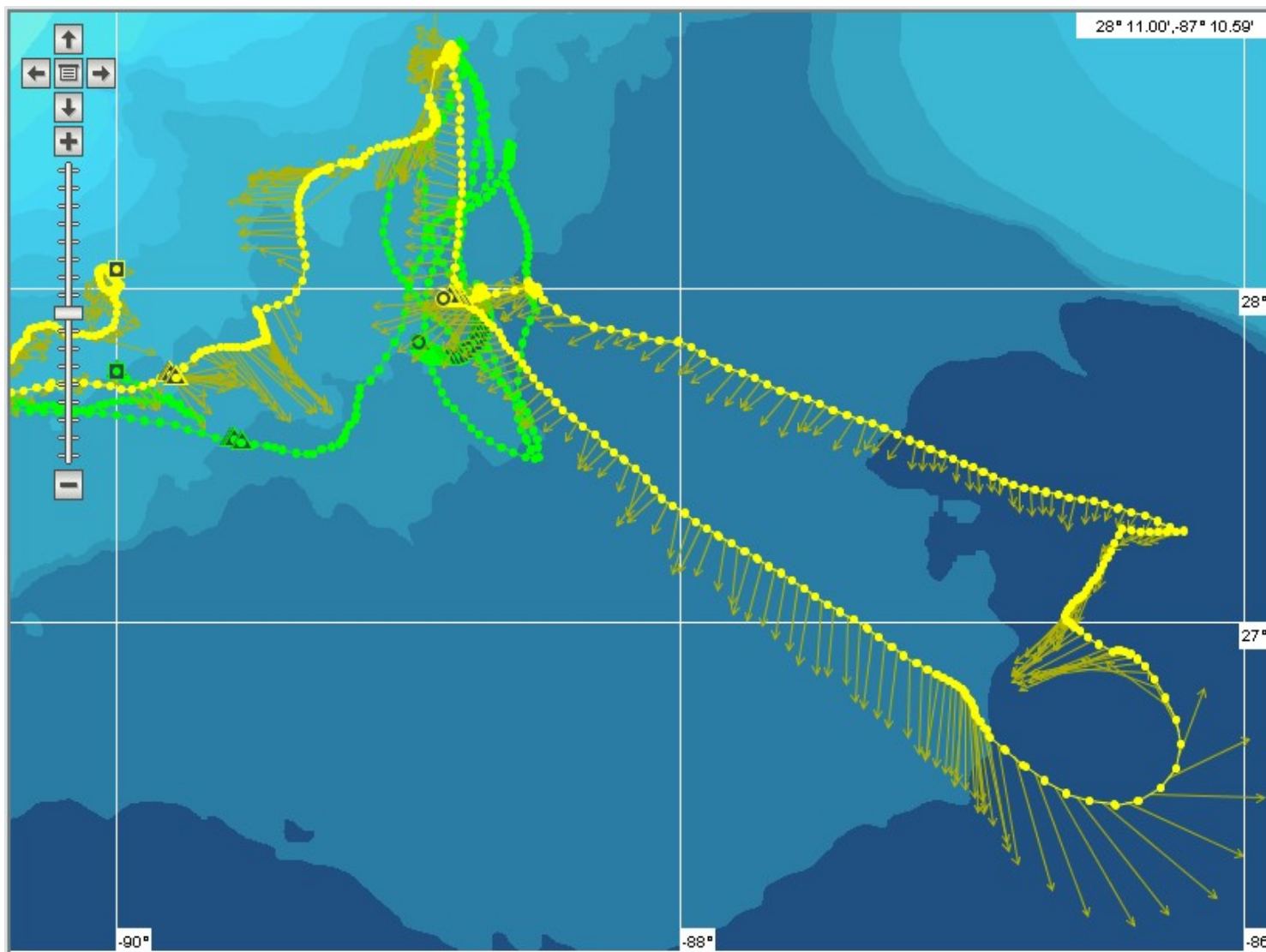
Profiling Float
-red-





Gulf of Mexico Mission

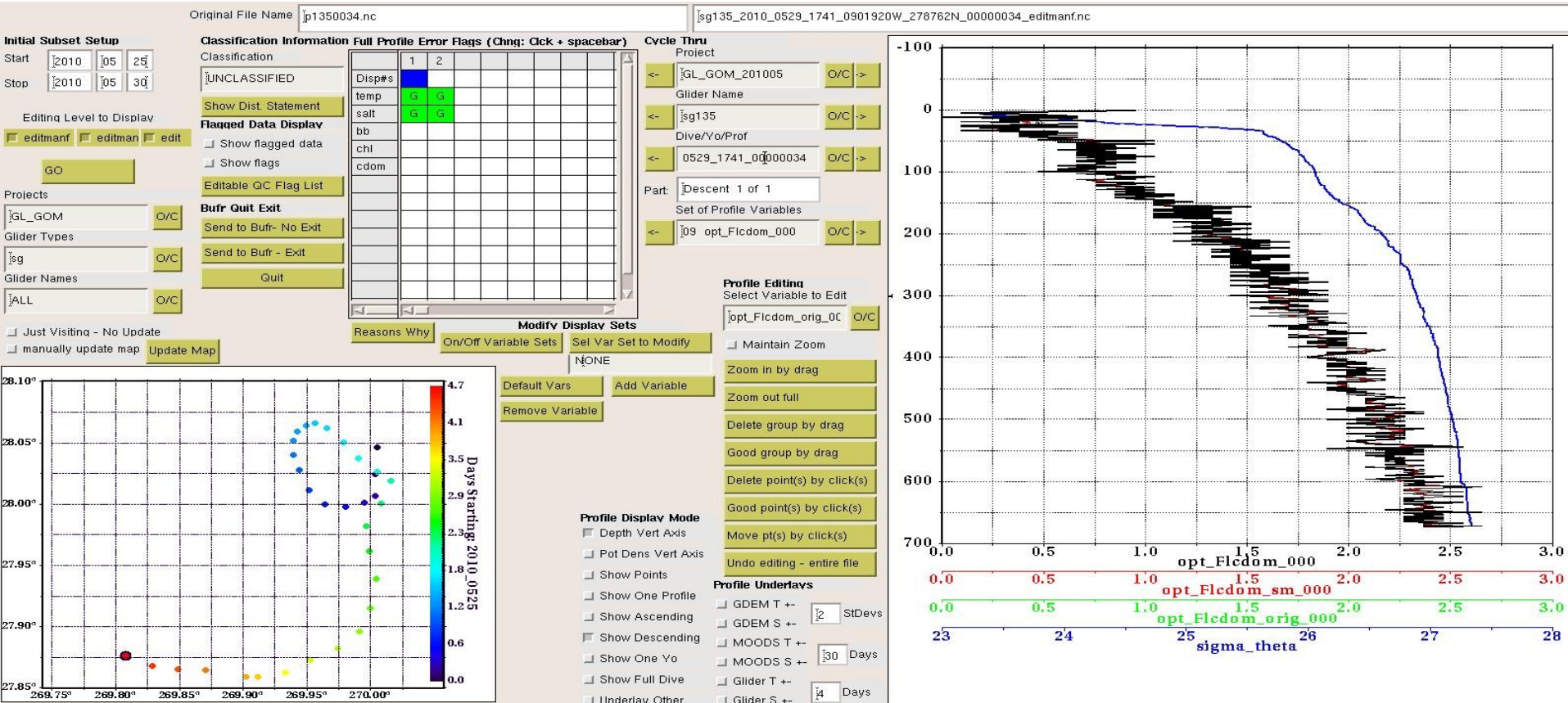
Depth Averaged Currents





Gulf of Mexico Mission

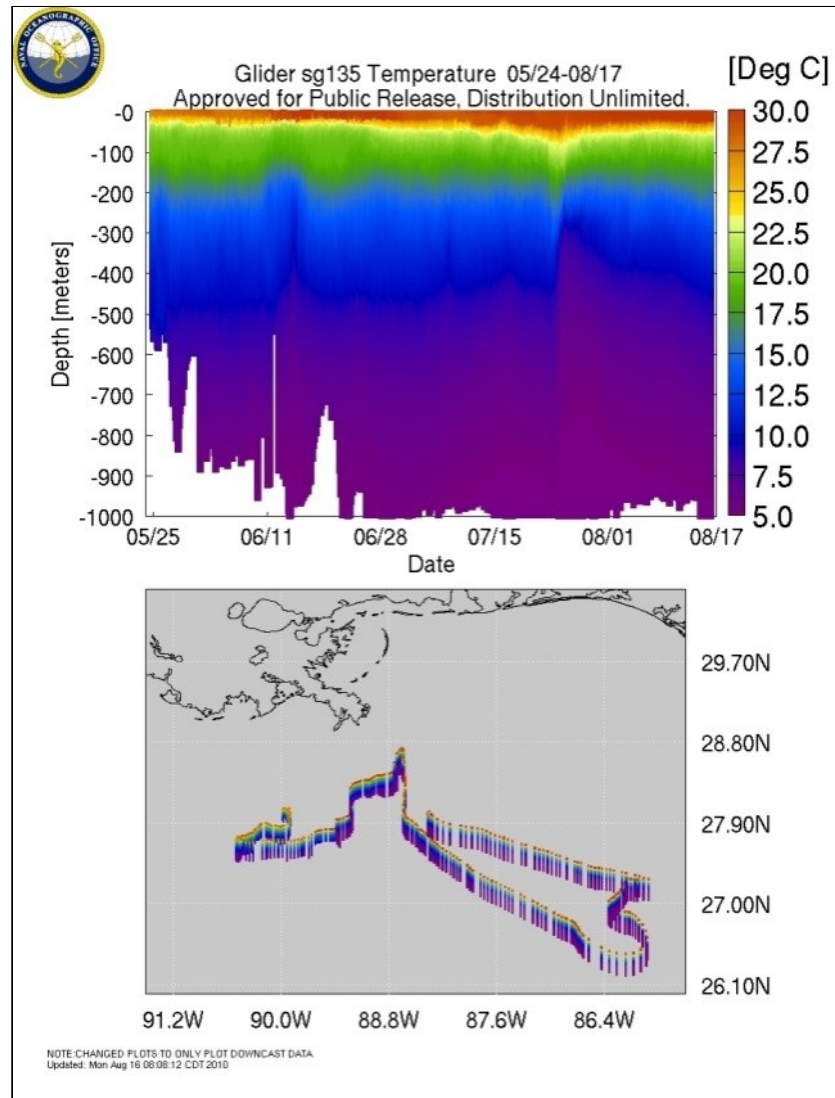
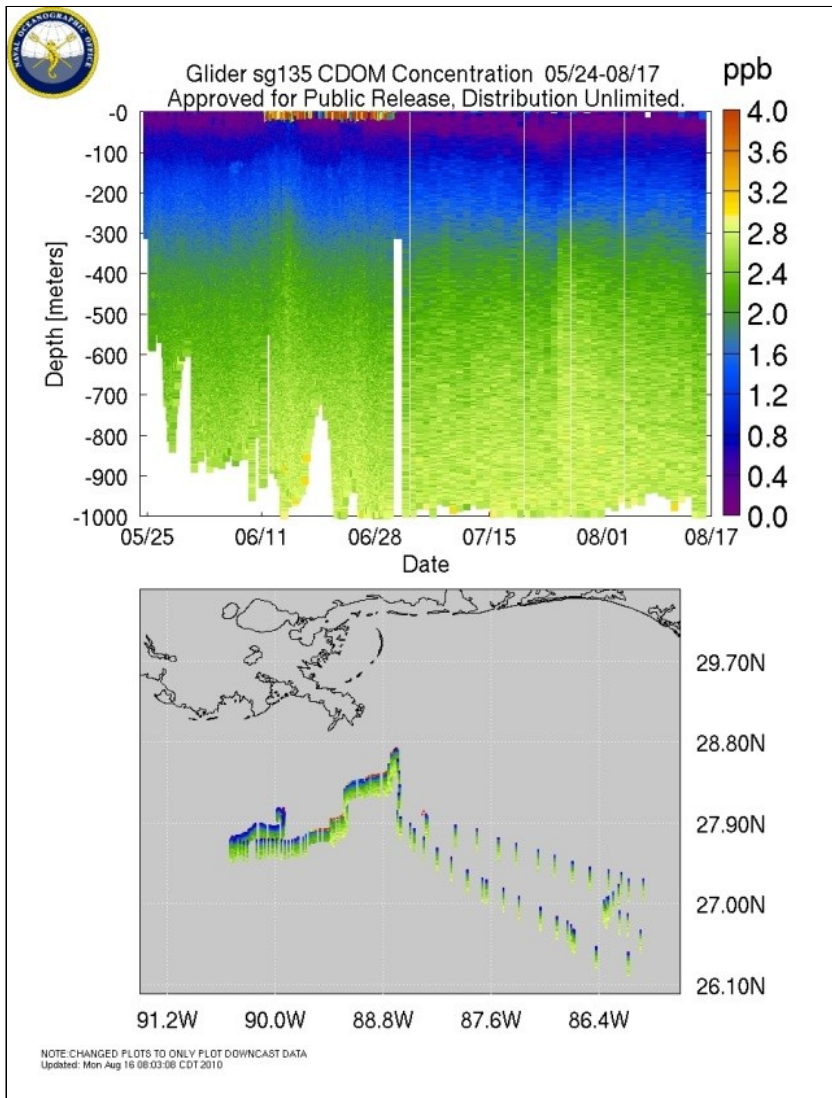
Typical CDOM Profile





Gulf of Mexico Mission

SG135 – CDOM and Temperature Profiles





Gulf of Mexico Mission

SG135 – Recovery Photos





Fleet Support Mission





Fleet Support Mission





NAVOCEANO Glider Operations

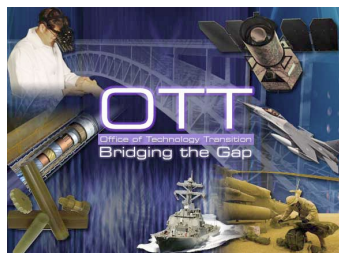


- 2008 Philippine Sea 6014
- 2008 Clear Horizon 238
- 2009 South China Sea 1728
- 2008 SHAMALEX 09-1 2682
- 2009 Arabian Gauntlet 2810
- 2009 SHAMALEX 09-2 1280
- 2009 Arctic 1356
- 2009 Philippine Sea 5234
- 2010 Arctic 888
- 2010 Gulf of Mexico 1700
- 2010 Valiant Shield 2010 618
- 2010 Arctic 182
- 2010 Philippine Sea 192

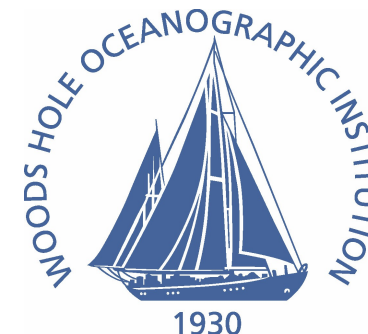
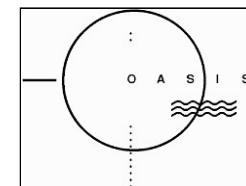
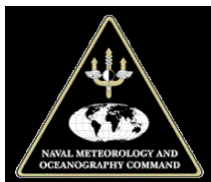
39,872
profiles as of
Dec 2010



Transition Partnerships

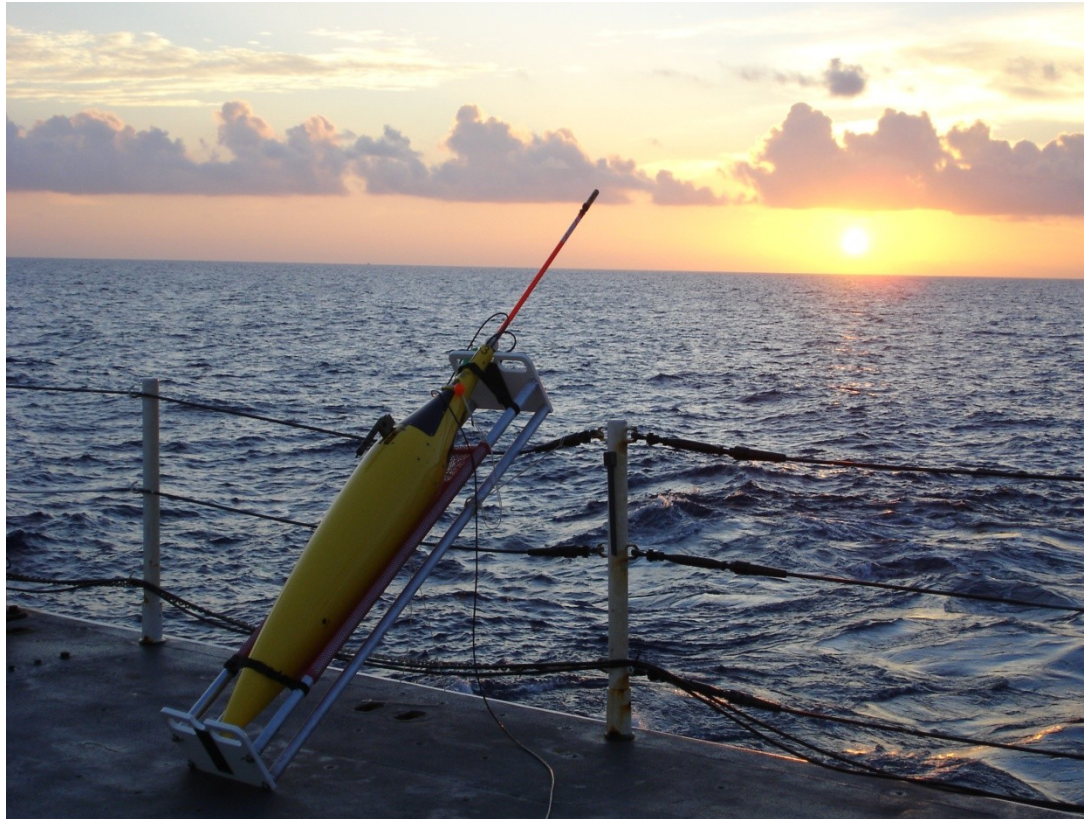


*" a successful story of cooperation
and collaboration with the R&D community"*





Ocean Glider Program



Questions?