

Simulating gliders

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Outline

- 1 Introduction
- 2 The models
- 3 Results
- 4 GTI compared with real glider data
- 5 Conclusions

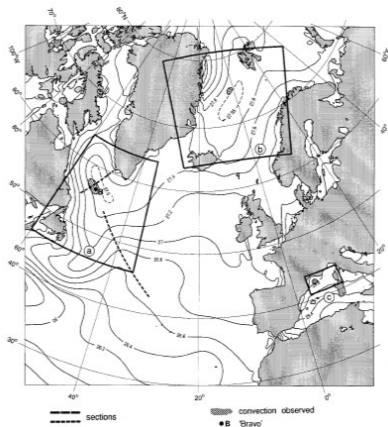


Why simulating?

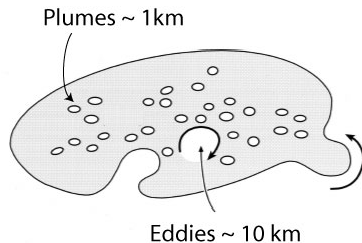
- No gliders out there yet,
- Examining observational capabilities,
- Evaluating sampling strategies.



Background



(Marshall & Schott, 1999)

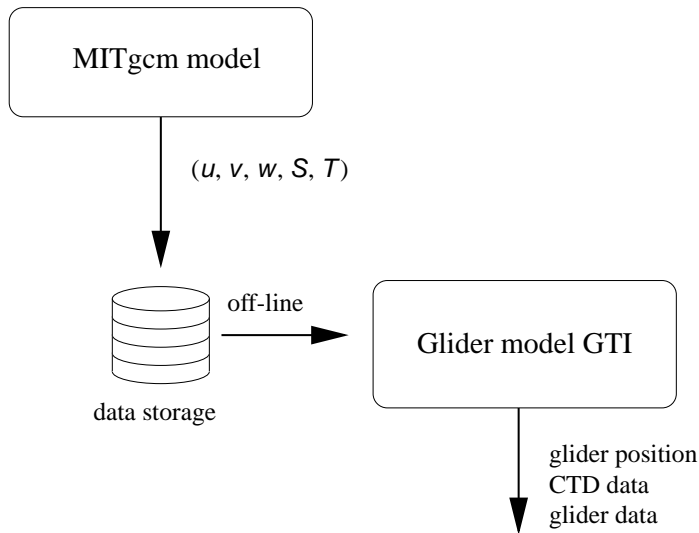


(Marshall & Schott, 1999)

- Convective mixing



Model overview



MITgcm model highlights

- non-hydrostatic,
- curvilinear grid,
- netcdf output,
- constant viscosity,
- freely available.

Web: <http://mitgcm.org>

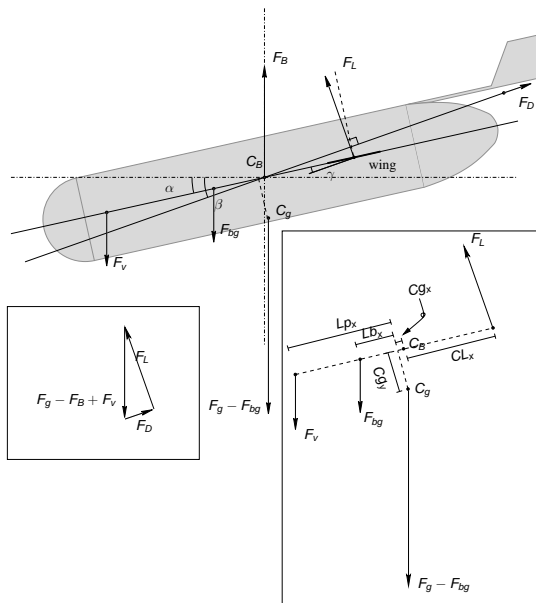


GTI model highlights

- considers all forces on glider,
- looks up in netcdf u , v , w using cubic interpolation,
- and T and S using tri-linear interpolation,
- user prescribed waypoints, gliding angles etc.,
- freely available from our website,
- C-code.



GTI model highlights



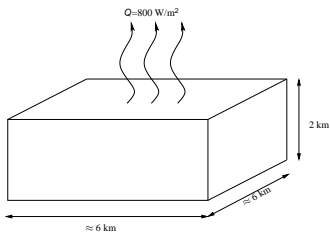
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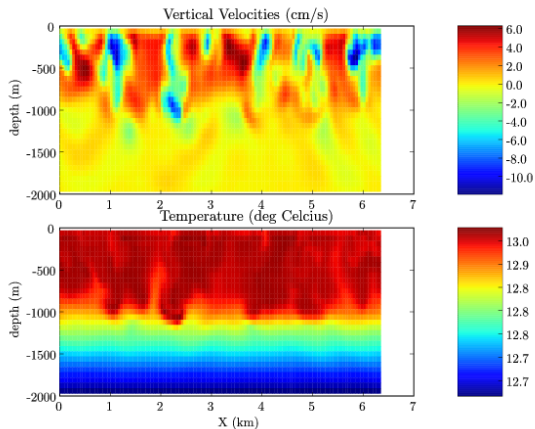
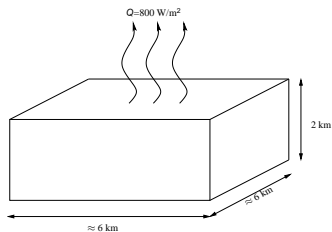
Web: <http://www.noc.soton.ac.uk/omf/lmm/glider>



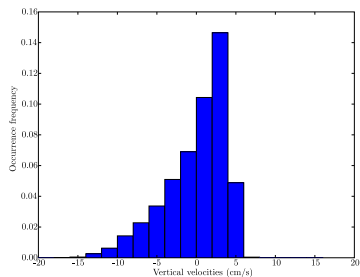
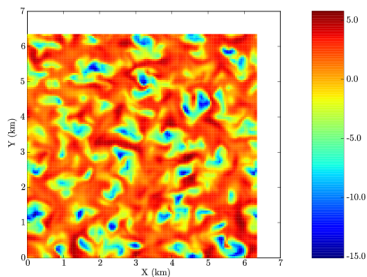
Model setup



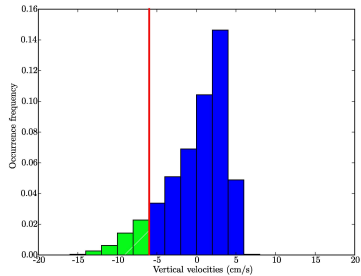
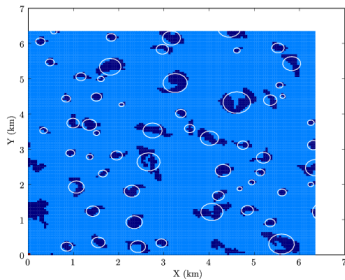
Model setup



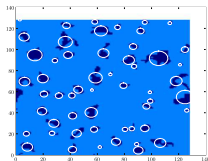
Plumes



Plumes



Some numbers...

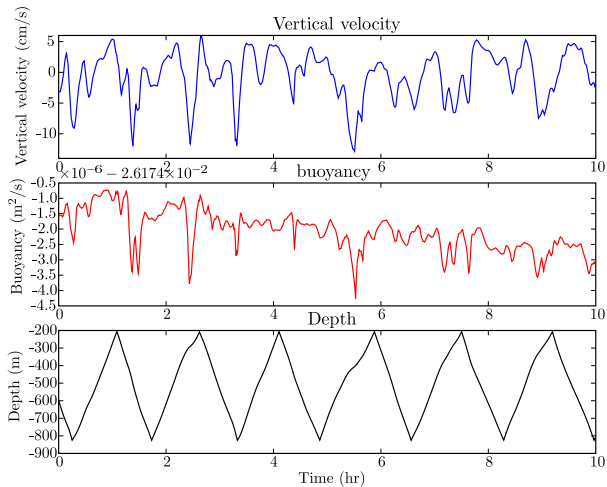


Plume density:	0.11	-
Average plume size:	≈ 300	m
Number of plumes:	59	-
Averaged distance between plumes:	≈ 2	km

Can we measure these numbers from glider data?

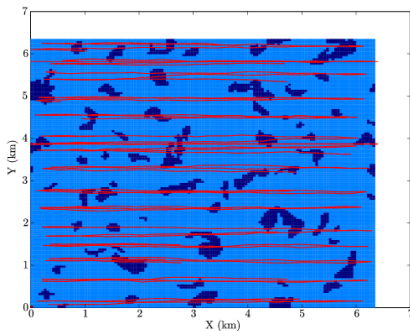


Glider time series...



Plume density

Using 15 gliders:



Plume density MITgcm: 0.11

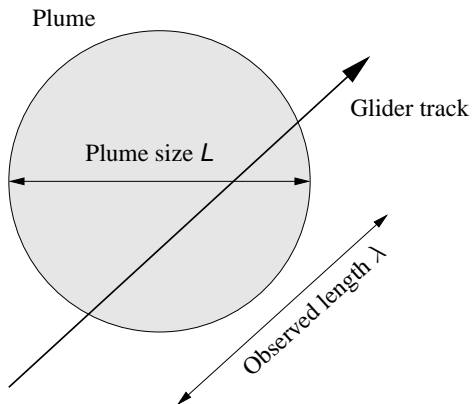
Plume density GTI: 0.11

plumes MITgcm: 59

plumes GTI: 67



Plume sizes

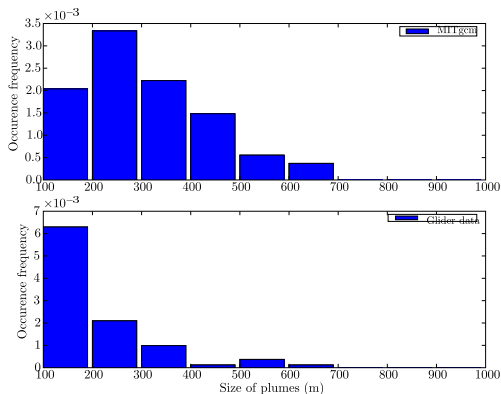


Expected value observed length:

$$E(\lambda) = \frac{\pi L}{4}$$



Plume sizes



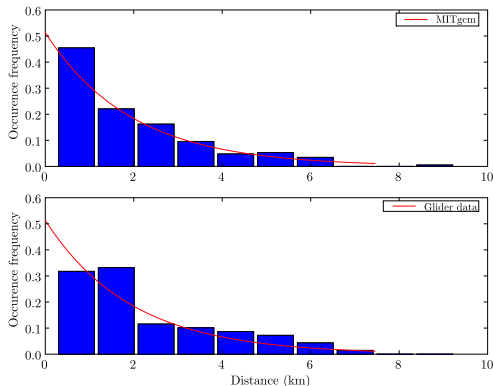
Average plume size MITgcm : 304 m

Average **observed** plume size GTI : 212 m

Average plume size GTI : 270 m



Plume–Plume distances



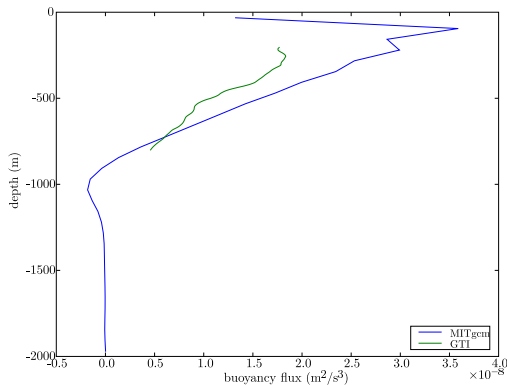
Average plume–plume distance MITgcm: 1.9 km

Average plume–plume distance GTI : 2.3 km



Buoyancy fluxes

$$\text{Buoyancy flux} = \overline{w'b'}$$



- Need many data to compute averages
- Need high quality estimates of vertical water velocities



Vertical velocity estimate

Vertical velocity of glider with respect to fixed reference frame:

$$w \approx \frac{1}{\rho g} \frac{dP}{dt}$$

which can be decomposed into:

$$W = w_{\text{glider}} + w_{\text{ambient water}}$$

What is w_{glider} ?



Vertical velocity estimate

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Optimally tuned glider dynamics model yields best estimate for vertical velocity from pressure fluctuations.



Tuning the GTI model

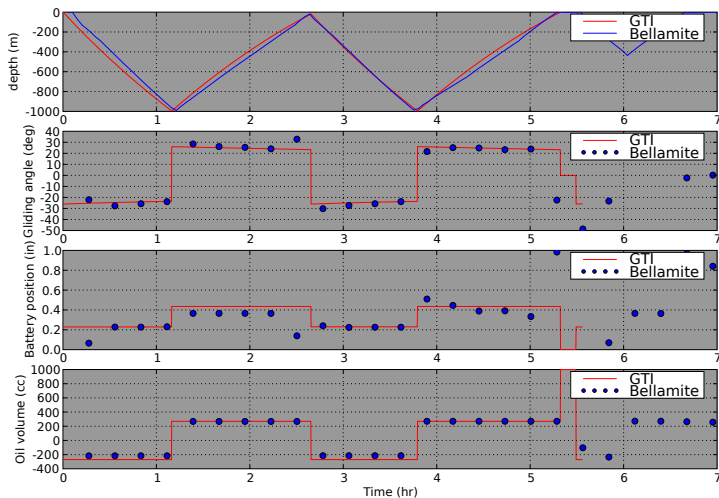
Comparing real glider data (*Bellamite* Mallorca trials April 2006) with GTI model:

Tuning paramters (short list):

- mass
- volume
- drag coefficients
- centre of mass(es)
- battery pack position
- ...



Data from GTI model and a mission from Bellamite



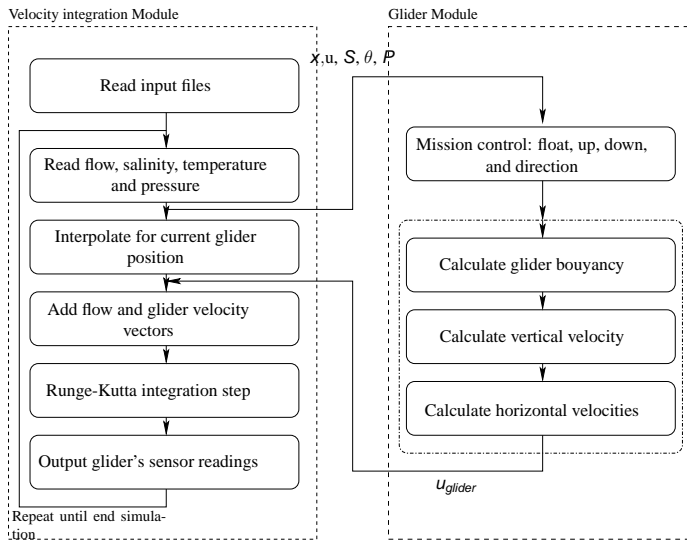
Conclusions

GTI:

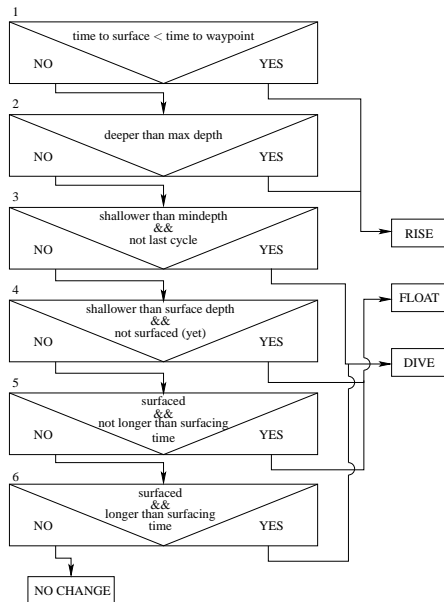
- Research tool
 - What to expect from glider data when flown in a convective area?
 - Evaluating sampling strategies.
- Tuning glider's dynamic model
 - Allows accurate as possible vertical flow velocity estimates.



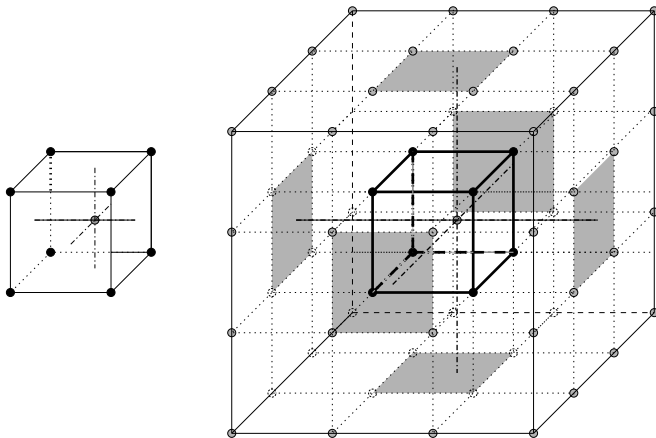
GTI model overview



GTI mission control



MITgcm data interpolation



The equations...

The vertical and horizontal components of the force balance:

$$\begin{aligned} F_g - F_B + F_v - \cos \beta F_L - \sin \beta F_D &= 0 \\ \cos \beta F_D - \sin \beta D_L &= 0 \end{aligned}$$

The lift force (thin plate-shaped wings):

$$F_L = \pi \gamma \rho A_w U^2$$

The drag force F_D

$$F_D = \frac{1}{2} C_{dg} \rho A_g U^2$$

Torque balance:

$$\begin{aligned} \cos \alpha (F_g - F_{bg}) C g_x + \cos \alpha F_v L p_x + \cos \alpha F_{bg} L b_x \\ - \sin \alpha F_g C g_y + \cos \gamma F_L C_{Lx} = 0. \end{aligned}$$



The equations...

$$\gamma = \frac{C_{dg}A_g}{2\pi A_w \tan(\alpha + \gamma)}$$

$$\tan \alpha = \frac{(F_g - F_{gb})Cg_x + \cos^2 \gamma C_{Lx}(F_g - F_B + F_V) + Lb_x F_{gb} + Lp_x F_V}{(F_g - F_{gb})Cg_y + \cos \gamma \sin \gamma C_{Lx}(F_g - F_B + F_V)}$$

- 1 set $\gamma = 0$
- 2 calculate α
- 3 calculate γ
- 4 loop back to 2, unless converged.

